

Lecture XXI

Solution by Diagonalization

The homogeneous linear system $\mathbf{X}' = \mathbf{A}\mathbf{X}$ in which each x'_j is expressed as a linear combination of x_1, x_2, \dots, x_n is said to be **coupled**. If the coefficient matrix \mathbf{A} is diagonalizable, then the system can be uncoupled in that each x'_j can be expressed solely in terms of x_j . If the matrix \mathbf{A} has n linearly independent eigenvectors then we can find a matrix \mathbf{P} such that $\mathbf{P}^{-1}\mathbf{A}\mathbf{P} = \mathbf{D}$, where \mathbf{D} is a diagonal matrix whose entries are the eigenvalues of \mathbf{A} and \mathbf{P} is a matrix whose columns are the corresponding eigenvectors of \mathbf{A} . The procedure follows.

Given the homogeneous linear system of n ODEs

$$\mathbf{X}' = \mathbf{A}\mathbf{X},$$

where the eigenvalues of \mathbf{A} are distinctly $\lambda_1, \lambda_2, \dots, \lambda_n$ with corresponding eigenvectors $\mathbf{K}_1, \mathbf{K}_2, \dots, \mathbf{K}_n$, we can formulate the matrices \mathbf{P} and \mathbf{D} as

$$\mathbf{P} = \begin{bmatrix} | & | & & | \\ \mathbf{K}_1 & \mathbf{K}_2 & \cdots & \mathbf{K}_n \\ | & | & & | \end{bmatrix} \quad \text{and} \quad \mathbf{D} = \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{bmatrix}.$$

We can then simplify the system with the substitution $\mathbf{X} = \mathbf{P}\mathbf{Y}$

$$\mathbf{X}' = \mathbf{A}\mathbf{X}$$

$$\mathbf{P}\mathbf{Y}' = \mathbf{A}\mathbf{P}\mathbf{Y}$$

$$\mathbf{Y}' = \mathbf{P}^{-1}\mathbf{A}\mathbf{P}\mathbf{Y}$$

$$\mathbf{Y}' = \mathbf{D}\mathbf{Y}.$$

The solution of the system $\mathbf{Y}' = \mathbf{D}\mathbf{Y}$ is obviously

$$\mathbf{Y} = \begin{bmatrix} c_1 e^{\lambda_1 t} \\ c_2 e^{\lambda_2 t} \\ \vdots \\ c_n e^{\lambda_n t} \end{bmatrix},$$

and so we can obtain the solution vector \mathbf{X} then using $\mathbf{X} = \mathbf{P}\mathbf{Y}$.

Lecture Problems (§10.3): 2, 4

Tutorial Problems (§10.3): 6, 7, 8

Suggested Problems (§10.3): 1, 3, 5

BONUS NOTES

None.

REFERENCES

Zill, D. G., & Wright, W. S. (2014). *Advanced Engineering Mathematics* (5th ed.). Burlington, MA: Jones & Bartlett Learning.